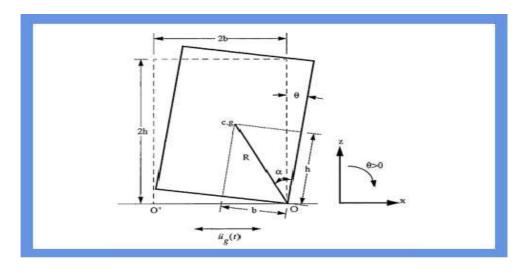


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Theory:



The equations that govern the rocking motion under the simultaneous presence of,

 $\ddot{u}_{g}(t)$ -- horizontal ground accelaration and,

 $\ddot{v}_{g}(t)$ -- vertical ground acceleration are

$$I_{o}\ddot{\theta}_{t} + mg\left[1 + \frac{\ddot{v}_{g}(t)}{g}\right]R\sin(-\alpha - \theta) = -m\ddot{u}_{g}(t)R\cos(-\alpha - \theta), \theta < 0$$

and,

$$I_{o}\ddot{\theta}_{t} + mg\left[1 + \frac{\ddot{v}_{g}(t)}{g}\right]R\sin(\alpha - \theta) = -m\ddot{u}_{g}(t)R\cos(\alpha - \theta), \theta > 0$$

For Rectangular blocks,

 $I_0 = (4/3)mR^2$ [where, m = Mass of the Block.]

The above two equations are linearized to get the time history of angular displacement $\theta(t) = A_1 \sinh(pt) + A_2 \cosh(pt) - \alpha + \frac{1}{1 + \frac{\omega_p^2}{p^2}} \frac{a_p}{g} \sin(\omega_p t + \psi), \theta < 0$

and,

$$\begin{split} \theta(t) &= A_3 \sinh(pt) + A_4 \cosh(pt) + \alpha + \frac{1}{1 + \frac{\omega_p^2}{p^2}} \frac{a_p}{g} \sin\left(\omega_p t + \psi\right), \theta > 0 \end{split}$$

Where,

$$\begin{split} A_1 &= A_3 = \frac{\theta_o}{p} - \alpha \frac{\frac{\omega_p}{p}}{1 + \frac{\omega_p^2}{p^2}} \frac{\cos{(\psi)}}{\sin{(\psi)}} \\ A_2 &= \theta_o + \alpha - \frac{\alpha}{1 + \frac{\omega_p^2}{p^2}} \\ A_4 &= \theta_o - \alpha - \frac{\alpha}{1 + \frac{\omega_p^2}{p^2}} \\ p &= \sqrt{\frac{3g}{4R}} \end{split}$$

where,

g = Frequency.

 $\psi = sin^{-1} \left[{^{\alpha g}}/{a_p} \right]$

http://eerc.iiit.ac.in http://cite.iiit.ac.in http://iiit.ac.in/ contact: eerc@iiit.ac.in